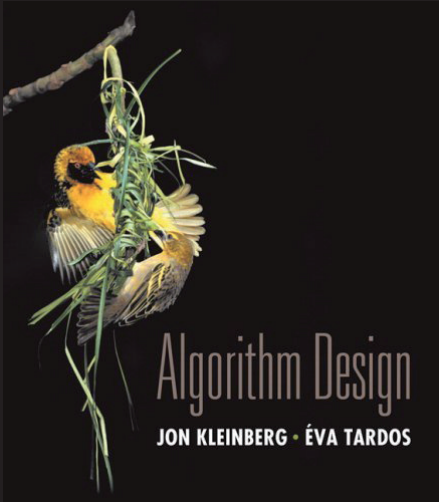


Chapter 6

Dynamic Programming



Slides by Kevin Wayne.
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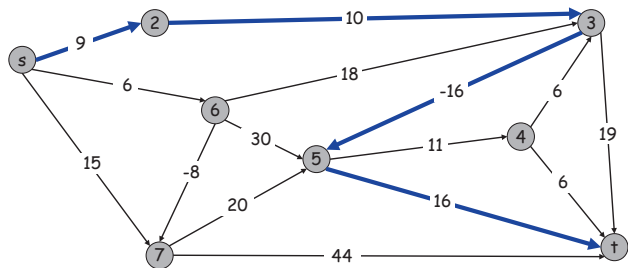
6.8 Shortest Paths

Shortest Paths

Shortest path problem. Given a directed graph $G = (V, E)$, with edge weights c_{vw} , find shortest path from node s to node t .

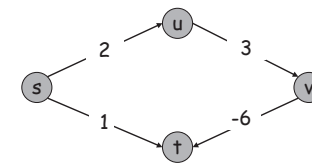
allow negative weights

Ex. Nodes represent agents in a financial setting and c_{vw} is cost of transaction in which we buy from agent v and sell immediately to w .

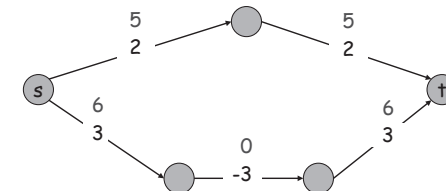


Shortest Paths: Failed Attempts

Dijkstra. Can fail if negative edge costs.

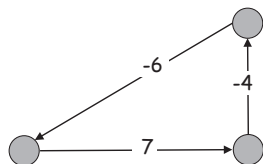


Re-weighting. Adding a constant to every edge weight can fail.

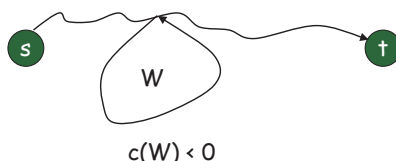


Shortest Paths: Negative Cost Cycles

Negative cost cycle.



Observation. If some path from s to t contains a negative cost cycle, there does not exist a shortest s - t path; otherwise, there exists one that is simple.



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Shortest Paths: Dynamic Programming

Def. $OPT(i, v)$ = length of shortest v - t path P using at most i edges.

- Case 1: P uses at most $i-1$ edges.
 - $OPT(i, v) = OPT(i-1, v)$
- Case 2: P uses exactly i edges.
 - if (v, w) is first edge, then OPT uses (v, w) , and then selects best w - t path using at most $i-1$ edges

$$OPT(i, v) = \begin{cases} 0 & \text{if } i=0 \\ \min \left\{ OPT(i-1, v), \min_{(v,w) \in E} \{ OPT(i-1, w) + c_{vw} \} \right\} & \text{otherwise} \end{cases}$$

Remark. By previous observation, if no negative cycles, then $OPT(n-1, v)$ = length of shortest v - t path.

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Shortest Paths: Implementation

```
Shortest-Path( $G, t$ ) {
  foreach node  $v \in V$ 
     $M[0, v] \leftarrow \infty$ 
   $M[0, t] \leftarrow 0$ 

  for  $i = 1$  to  $n-1$ 
    foreach node  $v \in V$ 
       $M[i, v] \leftarrow M[i-1, v]$ 
    foreach edge  $(v, w) \in E$ 
       $M[i, v] \leftarrow \min \{ M[i, v], M[i-1, w] + c_{vw} \}$ 
}
```

Analysis. $\Theta(mn)$ time, $\Theta(n^2)$ space.

Finding the shortest paths. Maintain a "successor" for each table entry.

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Shortest Paths: Practical Improvements

Practical improvements.

- Maintain only one array $M[v]$ = shortest v - t path that we have found so far.
- No need to check edges of the form (v, w) unless $M[w]$ changed in previous iteration.

Theorem. Throughout the algorithm, $M[v]$ is length of some v - t path, and after i rounds of updates, the value $M[v]$ is no larger than the length of shortest v - t path using $\leq i$ edges.

Overall impact.

- Memory: $O(m + n)$.
- Running time: $O(mn)$ worst case, but substantially faster in practice.

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```

Push-Based-Shortest-Path(G, s, t) {
  foreach node v ∈ V {
    M[v] ← ∞
    successor[v] ← ∅
  }

  M[t] = 0
  for i = 1 to n-1 {
    foreach node w ∈ V {
      if (M[w] has been updated in previous iteration) {
        foreach node v such that (v, w) ∈ E {
          if (M[v] > M[w] + cvw) {
            M[v] ← M[w] + cvw
            successor[v] ← w
          }
        }
      }
    }
    If no M[w] value changed in iteration i, stop.
  }
}
    
```

6.10 Negative Cycles in a Graph

Detecting Negative Cycles

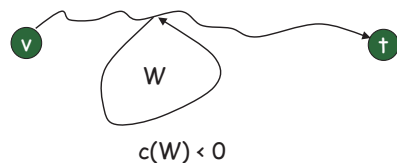
Lemma. If $OPT(n,v) = OPT(n-1,v)$ for all v , then no negative cycles.

Pf. Bellman-Ford algorithm.

Lemma. If $OPT(n,v) < OPT(n-1,v)$ for some node v , then (any) shortest path from v to t contains a cycle W . Moreover W has negative cost.

Pf. (by contradiction)

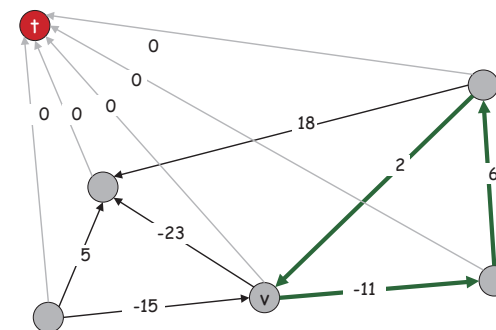
- Since $OPT(n,v) < OPT(n-1,v)$, we know P has exactly n edges.
- By pigeonhole principle, P must contain a directed cycle W .
- Deleting W yields a v - t path with $< n$ edges $\Rightarrow W$ has negative cost.



Detecting Negative Cycles

Theorem. Can detect negative cost cycle in $O(mn)$ time.

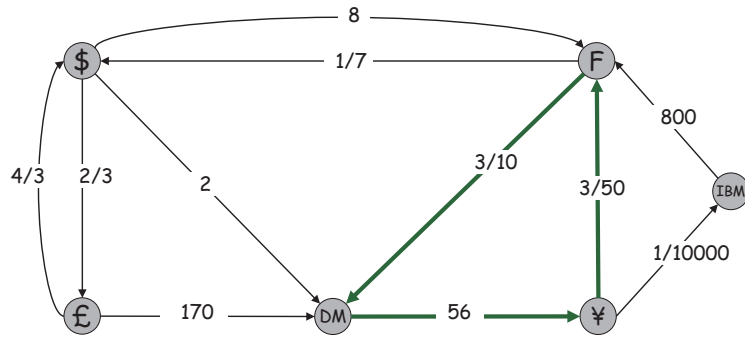
- Add new node t and connect all nodes to t with 0-cost edge.
- Check if $OPT(n, v) = OPT(n-1, v)$ for all nodes v .
 - if yes, then no negative cycles
 - if no, then extract cycle from shortest path from v to t



Detecting Negative Cycles: Application

Currency conversion. Given n currencies and exchange rates between pairs of currencies, is there an arbitrage opportunity?

Remark. Fastest algorithm very valuable!



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Detecting Negative Cycles: Summary

Bellman-Ford. $O(mn)$ time, $O(m + n)$ space.

- Run Bellman-Ford for n iterations (instead of $n-1$).
- Upon termination, Bellman-Ford successor variables trace a negative cycle if one exists.
- See p. 304 for improved version and early termination rule.

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