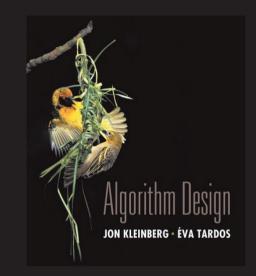
Soviet Rail Network, 1955



Chapter 7

Network Flow



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Maximum Flow and Minimum Cut

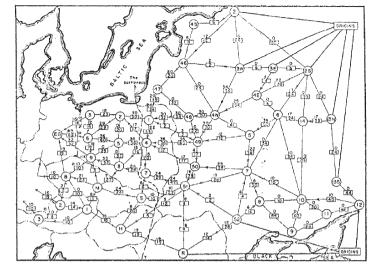
Max flow and min cut.

- . Two very rich algorithmic problems.
- . Cornerstone problems in combinatorial optimization.
- Beautiful mathematical duality.

Nontrivial applications / reductions.

- Data mining.
- . Open-pit mining.
- Project selection.
- . Airline scheduling.
- Bipartite matching.
- Baseball elimination.
- Image segmentation.
- . Network connectivity.

- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- . Security of statistical data.
- . Network intrusion detection.
- Multi-camera scene reconstruction.
- Many many more ...



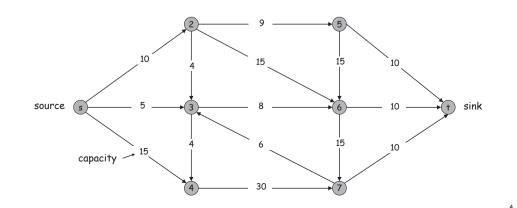
Reference: On the history of the transportation and maximum flow problems. Alexander Schrijver in Math Programming, 91: 3, 2002.

Minimum Cut Problem

2

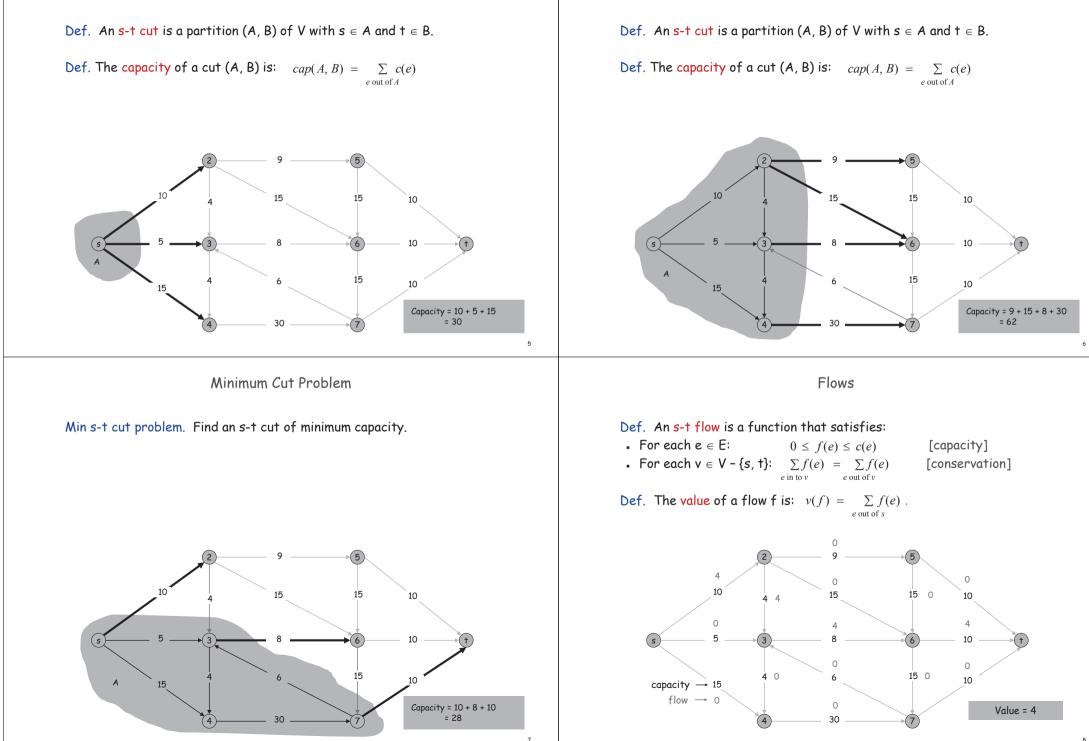
Flow network.

- Abstraction for material flowing through the edges.
- G = (V, E) = directed graph, no parallel edges.
- Two distinguished nodes: s = source, t = sink.
- c(e) = capacity of edge e.











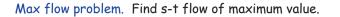
 $0 \leq f(e) \leq c(e)$

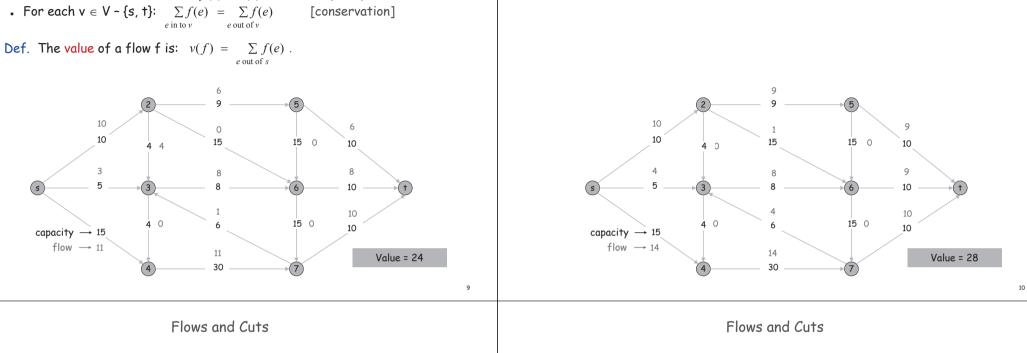
[capacity]

Def. An s-t flow is a function that satisfies:

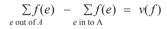
• For each $e \in E$:

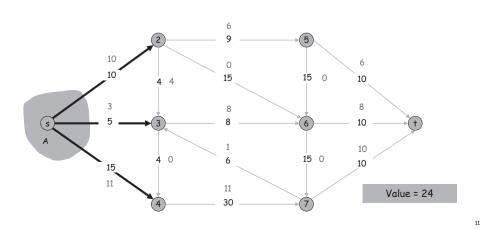
Maximum Flow Problem





Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

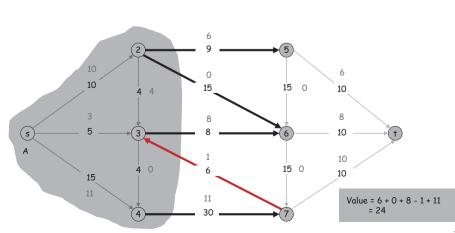




Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then, the net flow sent across the cut is equal to the amount leaving s.

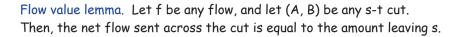
 $\sum_{\text{put of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$

e out of A

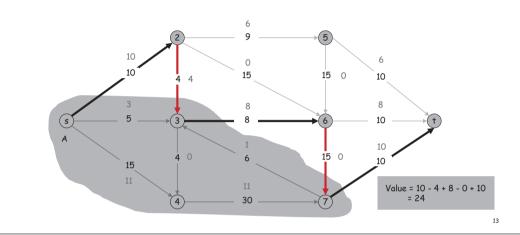


Flows and Cuts

Flows and Cuts



 $\sum_{e \text{ in to } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$ e out of A



Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then

 $\sum_{\text{ut of }A} f(e) - \sum_{e \text{ in to }A} f(e) = v(f).$

 $\sum f(e)$

e out of A

v(f) =

Pf.

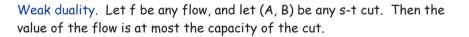
$$e \text{ out of } s$$
by flow conservation, all terms $\rightarrow = \sum_{v \in A} \left(\sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right)$

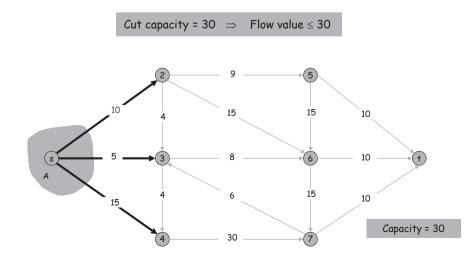
$$= \sum_{v \in A} f(e) - \sum_{v \in A} f(e).$$

e out of A

e in to A

Flows and Cuts



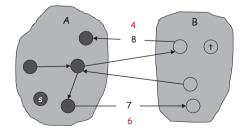


Flows and Cuts

Weak duality. Let f be any flow. Then, for any s-t cut (A, B) we have $v(f) \leq cap(A, B).$

Pf.

$$v(f) = \sum_{\substack{e \text{ out of } A}} f(e) - \sum_{\substack{e \text{ in to } A}} f(e)$$
$$\leq \sum_{\substack{e \text{ out of } A}} f(e)$$
$$\leq \sum_{\substack{e \text{ out of } A}} c(e)$$
$$= cap(A, B) \cdot$$

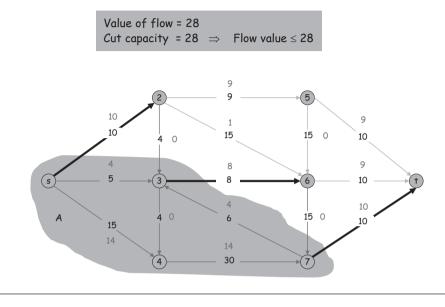


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Certificate of Optimality

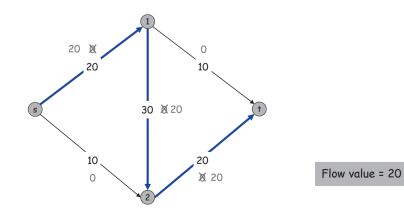
Corollary. Let f be any flow, and let (A, B) be any cut. If v(f) = cap(A, B), then f is a max flow and (A, B) is a min cut.



Towards a Max Flow Algorithm

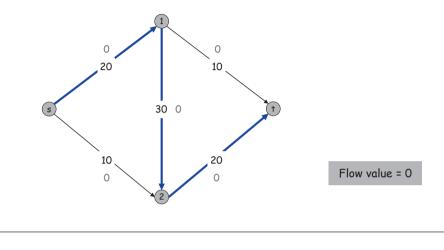
Greedy algorithm.

- Start with f(e) = 0 for all edge $e \in E$.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- . Repeat until you get stuck.



Greedy algorithm.

- Start with f(e) = 0 for all edge $e \in E$.
- Find an s-t path P where each edge has f(e) < c(e).
- Augment flow along path P.
- Repeat until you get stuck.





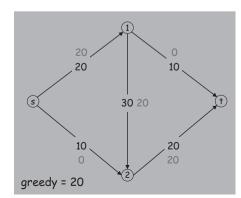
 \sim locally optimality \Rightarrow global optimality

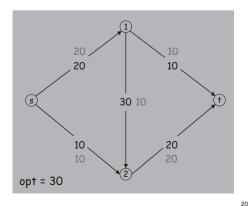
Greedy algorithm.

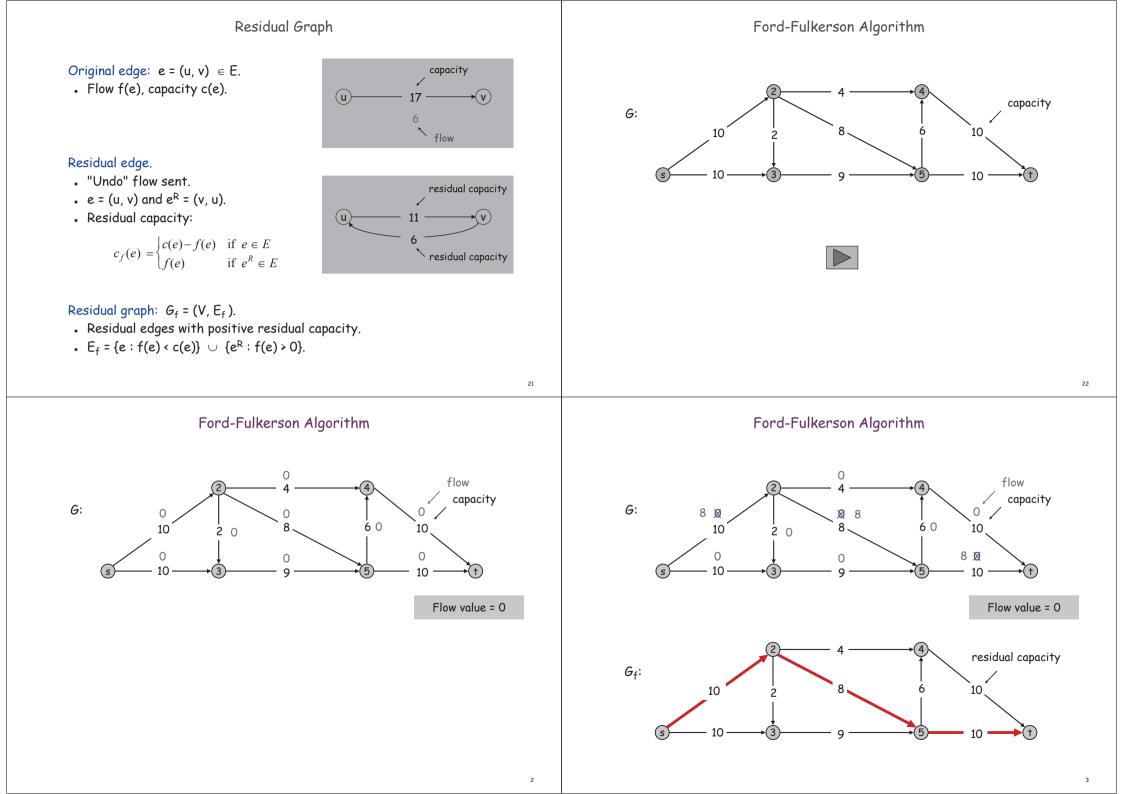
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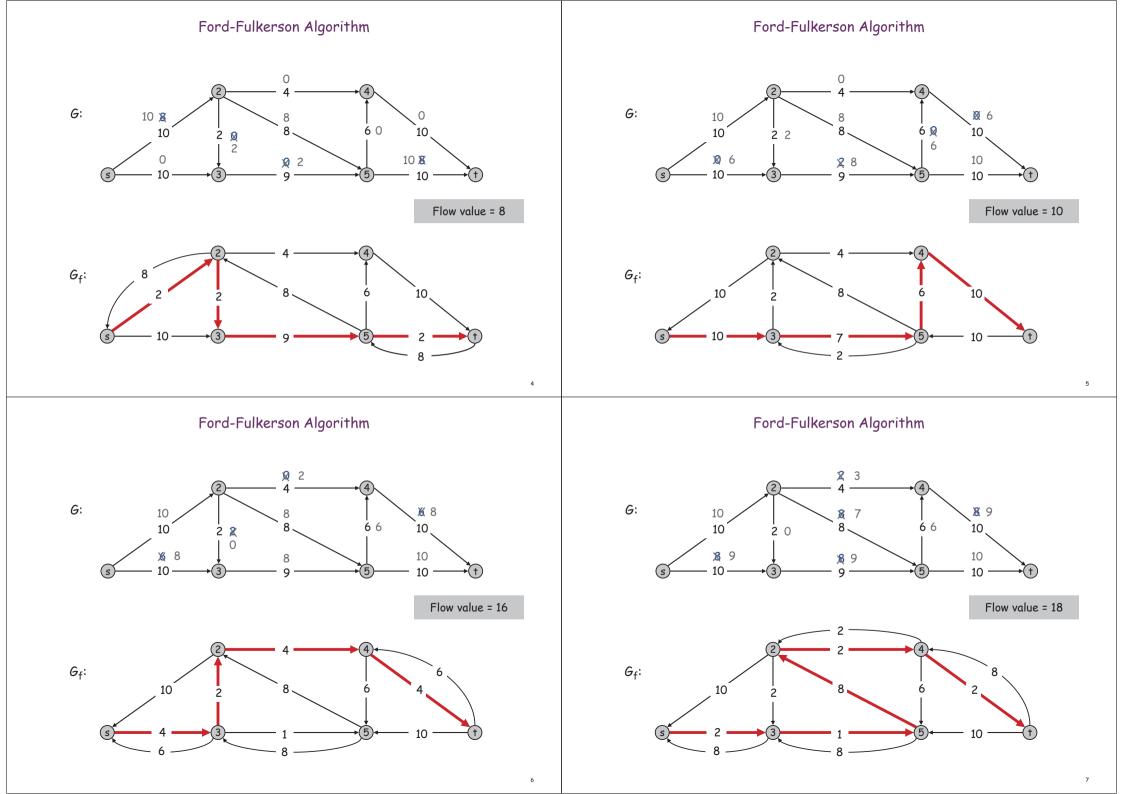
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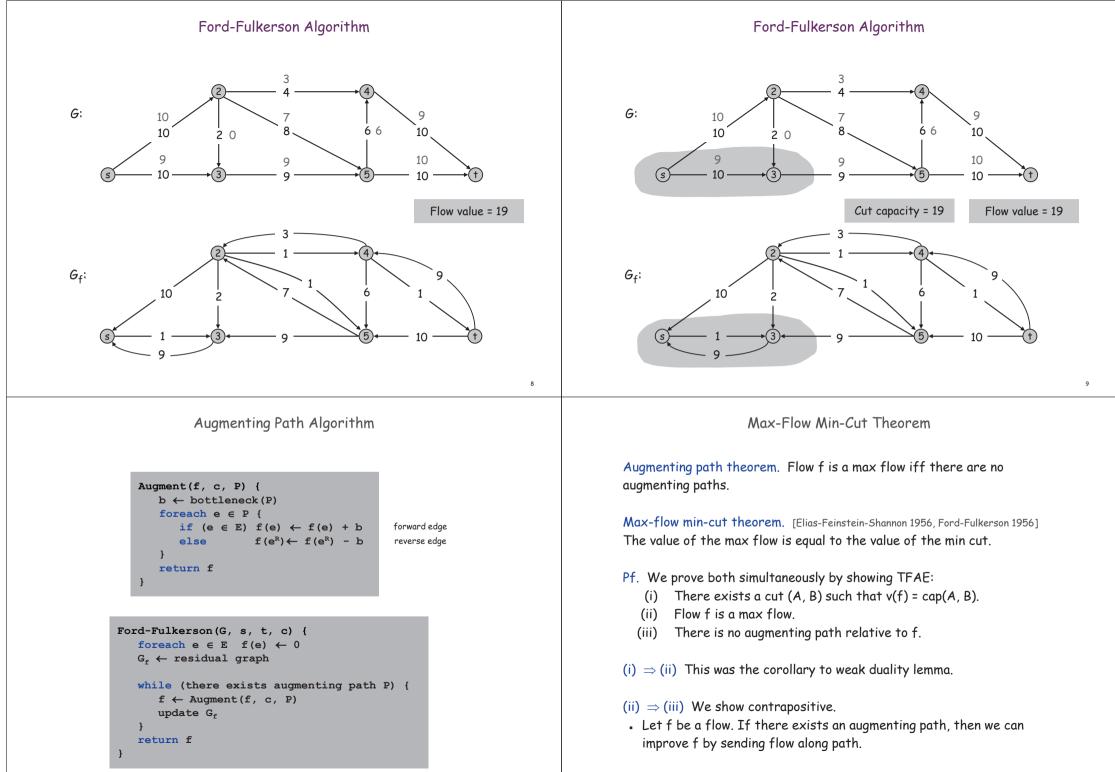
- Start with f(e) = 0 for all edge $e \in E$.
- Find an s-t path P where each edge has f(e) < c(e).
- . Augment flow along path P.
- Repeat until you get stuck.











Proof of Max-Flow Min-Cut Theorem **Running Time** (iii) \Rightarrow (i) Assumption. All capacities are integers between 1 and C. • Let f be a flow with no augmenting paths. • Let A be set of vertices reachable from s in residual graph. Invariant. Every flow value f(e) and every residual capacity $c_{f}(e)$ • By definition of $A, s \in A$. remains an integer throughout the algorithm. • By definition of $f, t \notin A$. Theorem. The algorithm terminates in at most $v(f^*) \leq nC$ iterations. Pf. Each augmentation increase value by at least 1. v(f) = $\sum f(e) - \sum f(e)$ e in to A $\Sigma c(e)$ Corollary. If C = 1, Ford-Fulkerson runs in O(mn) time. e out of A = cap(A, B)Integrality theorem. If all capacities are integers, then there exists a max flow f for which every flow value f(e) is an integer. Pf. Since algorithm terminates, theorem follows from invariant. original network 25 Ford-Fulkerson: Exponential Number of Augmentations Q. Is generic Ford-Fulkerson algorithm polynomial in input size? 7.3 Choosing Good Augmenting Paths m, n, and log C A. No. If max capacity is C, then algorithm can take C iterations. 1 🕅 1 X X 0 1 10 1 X 1 0 1 🕅

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Choosing Good Augmenting Paths

Use care when selecting augmenting paths.

- . Some choices lead to exponential algorithms.
- Clever choices lead to polynomial algorithms.
- If capacities are irrational, algorithm not guaranteed to terminate!

Goal: choose augmenting paths so that:

- . Can find augmenting paths efficiently.
- Few iterations.

}

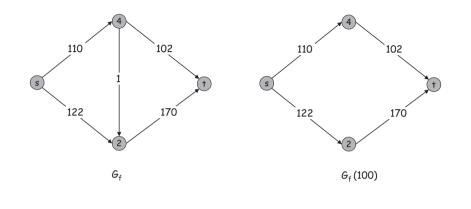
Choose augmenting paths with: [Edmonds-Karp 1972, Dinitz 1970]

- Max bottleneck capacity.
- Sufficiently large bottleneck capacity.
- Fewest number of edges.

Capacity Scaling

Intuition. Choosing path with highest bottleneck capacity increases flow by max possible amount.

- Don't worry about finding exact highest bottleneck path.
- Maintain scaling parameter Δ .
- Let $G_{f}(\Delta)$ be the subgraph of the residual graph consisting of only arcs with capacity at least Δ .



Capacity Scaling

```
Scaling-Max-Flow(G, s, t, c) {
    foreach e \in E f(e) \leftarrow 0
    \Delta \leftarrow smallest power of 2 greater than or equal to C
    G_{f} \leftarrow residual graph
    while (\Delta \ge 1) {
        G_{f}(\Delta) \leftarrow \Delta-residual graph
        while (there exists augmenting path P in G_{f}(\Delta)) {
             f \leftarrow augment(f, c, P)
            update G_f(\Delta)
        \Delta \leftarrow \Delta / 2
    3
    return f
```

Capacity Scaling: Correctness

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32

Assumption. All edge capacities are integers between 1 and C.

Integrality invariant. All flow and residual capacity values are integral.

Correctness. If the algorithm terminates, then f is a max flow. Pf.

- By integrality invariant, when $\Delta = 1 \implies G_f(\Delta) = G_f$.
- Upon termination of Δ = 1 phase, there are no augmenting paths.

Capacity Scaling: Running Time

Lemma 1. The outer while loop repeats $1 + \lceil \log_2 C \rceil$ times. Pf. Initially $C \le \Delta < 2C$. Δ decreases by a factor of 2 each iteration.

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then the value of the maximum flow is at most v(f) + m Δ . \leftarrow proof on next slide

Lemma 3. There are at most 2m augmentations per scaling phase.

- . Let f be the flow at the end of the previous scaling phase.
- L2 \Rightarrow v(f*) \leq v(f) + m (2 Δ).
- Each augmentation in a ${\vartriangle}$ -phase increases v(f) by at least ${\vartriangle}$.

Theorem. The scaling max-flow algorithm finds a max flow in $O(m \log C)$ augmentations. It can be implemented to run in $O(m^2 \log C)$ time.

Lemma 2. Let f be the flow at the end of a Δ -scaling phase. Then value of the maximum flow is at most v(f) + m Δ .

- Pf. (almost identical to proof of max-flow min-cut theorem)
- We show that at the end of a Δ -phase, there exists a cut (A, B) such that cap(A, B) $\leq v(f) + m \Delta$.
- . Choose A to be the set of nodes reachable from s in ${\sf G}_f(\Delta).$
- By definition of $A, s \in A$.
- By definition of f, $t \notin A$.

