

Query Processing (I)

April 28, 2023

DBMS: Operator execution

Purpose:

Execute a dataflow by operation on tuples and files.

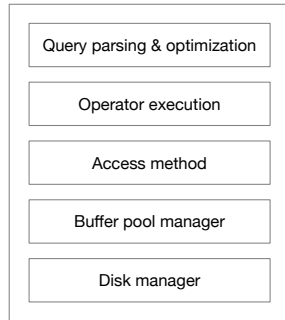
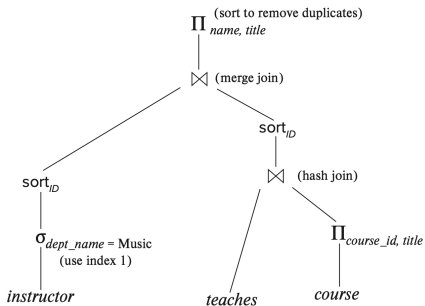
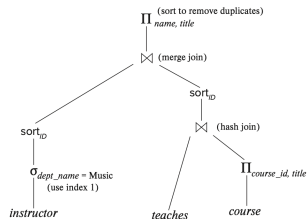
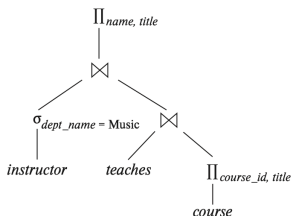


Figure: DBMS architecture

Query processing overview

```
SELECT name, title
FROM instructor natural join teaches
      natural join course
WHERE dept_name = 'Music';
```



SQL Query

Logical Plan

Physical plan

- Each node of a **logical plan** is a relational operator.
- Each node of a **physical plan** represents an **operator algorithm**.
- Data flows from the leaves of the physical plan tree **up towards** the root.

Notations

- Tables: R, S
- Tuples: t_r, t_s
- Number of tuples: $|R|, |S|$
- Number of pages: $P(R), P(S)$
- Number of available buffer pool pages: B
- Cost metric: *number of I/O's*

Sequential scan

- Scan table R sequentially and process the query
 - Selection over R
 - Projection of R without duplicate elimination
- I/O cost: $P(R)$
- Not counting the cost of writing the result out.
 - Maybe not needed – results may be pipelined into another operator.
 - Same for any algorithm discussed later.

Sorting

Why sorting

- Tuples in a table have no specific order.
- Query may require output be sorted.
 - E.g., `SELECT * from student ORDER BY credit DESC;`
- Several relational operators can be implemented efficiently with sorting.
 - E.g., duplication elimination, aggregation, merge join, set operations.
- **External sorting** is required when data cannot fit in memory.

External merge sorting

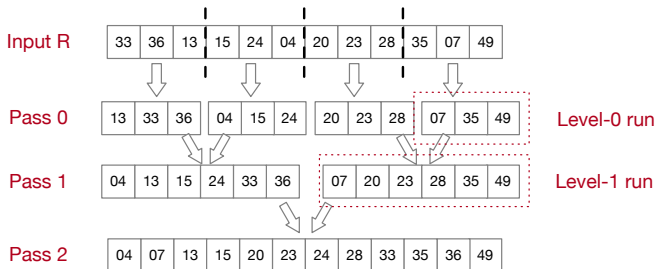
A **divide-and-conquer** approach to sort a large relation R that cannot fit in memory.

Recall that we have B pages available in the buffer pool.

- **Pass 0**: read B pages of R each time, **sort** them, and write out a **level-0 run**.
- **Pass 1**: **merge** $B - 1$ level-0 runs each time, and write out a **level-1 run**.
- **Pass 2**: **merge** $B - 1$ level-1 runs each time, and write out a **level-2 run**.
- ...
- **Final pass** produces one sorted run.

External merge example

- $B = 3$, i.e., 3 pages available in buffer pool.
- Each page holds only one tuple.
- In pass 0, all 3 pages are used for sorting.
- In pass i , where $i \geq 1$, 2 pages are used for input, and 1 page for output.



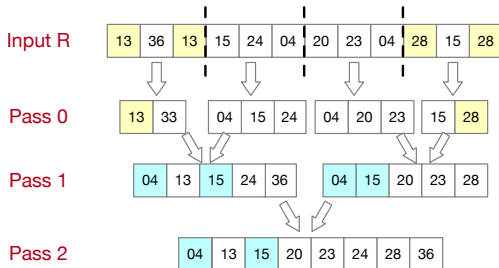
Cost analysis

#(Passes)	$\log_{B-1} \lceil P(R)/B \rceil + 1$
#(Read Pages)	$P(R) * (\log_{B-1} \lceil P(R)/B \rceil + 1)$
#(Write Pages)	$P(R) * \log_{B-1} \lceil P(R)/B \rceil$
Total cost	$2P(R) * \log_{B-1} \lceil P(R)/B \rceil + P(R)$

- **Pass 0**: read B pages of R each time, sort them, and write out a level-0 run.
- **Pass i** : merge $(B - 1)$ level- $(i - 1)$ runs each time, and write out a level- i run.
- Each pass read the entire relation and write it once.
- We do not include the output cost of the **final pass** as we have discussed.

Sort-based duplication elimination

1. Perform external merge sort.
2. Eliminate duplicates during sort and merge.
3. **Cost:** same cost as sorting.



Sort-based aggregation

- Sort the tuples on the **GROUP BY** attributes
- Perform a sequential scan over the sorted data to compute the aggregation.
 - This can be fused into the **final pass** of sorting.
- Apply **partial aggregation** on the fly.
- The output will be sorted on the attributes.
- **Cost**: same cost as sorting.

```
SELECT dept_name, AVG(salary)
FROM instructor
GROUP BY dept_name
```

Agg	Running value
MIN	min
MAX	max
COUNT	count
SUM	sum
AVG	(count, sum)

 Join

Naive nested loop join

1. for each tuple t_r in R do
2. for each tuple t_s in S do
3. if $\theta(t_r, t_s)$ then
4. add $t_r \bowtie t_s$ to the result

Figure: Algorithm for $R \bowtie_{\theta} S$

- The most basic join algorithm to compute join $R \bowtie_{\theta} S$.
- R: the **outer** table, S: the **inner** table.
- Require no indices and can be used with **any kind of join conditions**.

Cost analysis

- $P(R) + P(S)$: the buffer pool can hold both tables as input.
- $P(R) + |R| * P(S)$: $B = 3$. Use two buffer pool pages for input, and one page for output.

Example

A	B
10	a
20	b
20	c
40	d

R

A	C
50	e
20	f
20	g
30	h
40	i
50	j

S

A	B	C
20	b	f
20	b	g
20	c	f
20	c	g
40	d	i

$R \bowtie S$

- $|R| = 4$, $|S| = 6$, $P(R) = 2$, $P(S) = 3$.
- If $B = 3$ and R is the outer table, then $\#(I/O) = 14$.
- If $B = 3$ and S is the outer table, then $\#(I/O) = 15$.

Blocked nested loop join

1. **for each** page P_r in R **do**
2. **for each** page P_s in S **do**
3. **for each** tuple t_r in P_r **do**
4. **for each** tuple t_s in P_s **do**
5. **if** $\theta(t_r, t_s)$ **then**
6. add $t_r \bowtie t_s$ to the result

Figure: Improved algorithm for $R \bowtie_{\theta} S$

- Naive nested loop join is costly since for every tuple in the outer table R , we must do a sequentially scan of the inner table S .
- To maximize the utilization of buffer pool, process tables on a **per-page basis**, rather than on a **per-tuple basis**.

Example

A	B
10	a
20	b
20	c
40	d

R

A	C
50	e
20	f
20	g
30	h
40	i
50	j

S

A	B	C
20	b	f
20	b	g
20	c	f
20	c	g
40	d	i

$R \bowtie S$

- $|R| = 4$, $|S| = 6$
- $P(R) = 2$, $P(S) = 3$.
- If $B = 3$ and R is the outer table, then $\#(I/O) = 8$.
- If $B = 3$ and S is the outer table, then $\#(I/O) = 9$.

Cost analysis

- $P(R) + P(R) * P(S)$: use two buffer pool pages for input and another page for output.

In general, if B pages are available in the buffer pool for the join operation, then

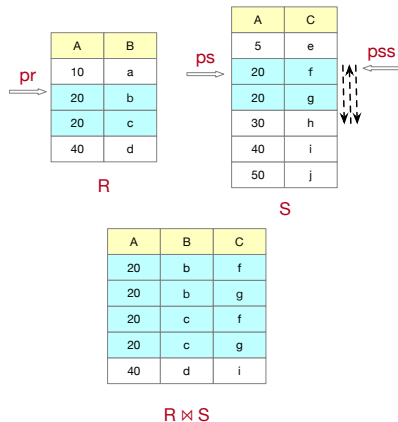
- Use $B - 2$ pages to scan the outer table R
- Use one page for inner table scan
- The rest page for buffering the output
- Total cost: $P(R) + \lceil P(R)/(B - 2) \rceil * P(S)$

➤ Merge join

- Require **equality predicate**, e.g., equi-joins or natural joins.
- If R or S is not sorted by the join attributes, then sort it first.
- All tuples with the same value on the joined attributes are in **consecutive** order.
- **Merge** scan the sorted tables and emit tuples that match.

Merge join

1. /* ps/pr points to the first tuple of R/S */
2. while pr \neq EOF & ps \neq EOF do
3. while $t_{pr}[A] < t_{ps}[A]$ do ++pr;
4. while $t_{pr}[A] > t_{ps}[A]$ do ++ps;
5. while $t_{pr}[A] = t_{ps}[A]$ do
6. pss := ps; /* set pss to the first match */
7. while $t_{pr}[A] = t_{pss}[A]$ do
8. add $t_{pr} \bowtie t_{pss}$ to result;
9. ++pss;
10. ++pr;
11. ps := pss; /* all matches processed, advance ps */



Cost analysis

- Most cases: Sorting + $P(R) + P(S)$.
- Assumption: Every set of match candidates in S can fit in buffer pool.
- Worst case: Sorting + $P(R) + P(R) * P(S)$
- Assumption: Everything joins and $B = 3$.

Sort-based set operations

- $R \cup S$, $R \cap S$, $R - S$ requires **duplication elimination** by default.
- Sort R and S in the same order.
- Scan the sorted R and S to produce the desired results in a similar way as in merge join.
- Both R and S require only one pass of scan.
- **Cost:** sorting + $P(R) + P(S)$

