

HMM in Wearable Computing

Presented by Cong Wang

Wearable Computing

What's that?



Motivation

- Wearable devices become a hit
- A wearable computing system with multi-sensors (gyroscope, accelerometer...)
- Action recognition & Energy-saving

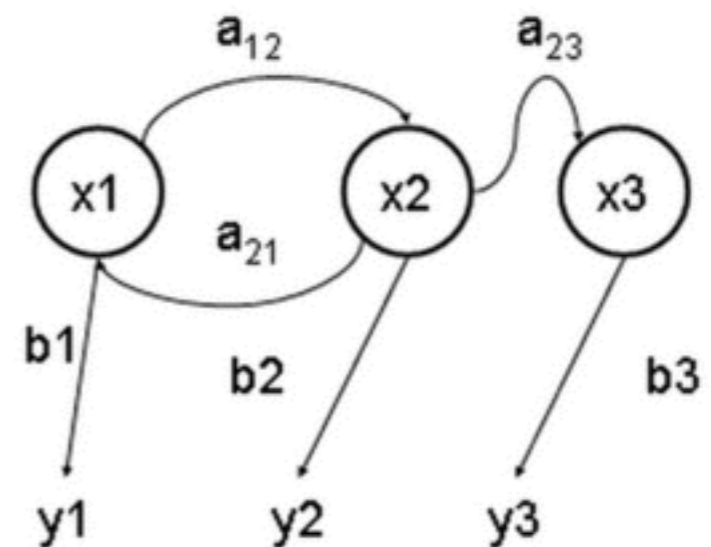
System

- Sensors(gyroscope,accelerometer)
- Arduino pro mini 320p
- Multiple data transmitted to Android



Hidden Markov Model(HMM)

- A statistic model
- **Invisible** hidden states
- **Visible** observed symbols
- Transition probabilities



Elements

- N —the number of hidden states
- Q —set of states $Q = \{1, 2, \dots, N\}$
- M —the number of symbols
- V —set of symbols $V = \{1, 2, \dots, M\}$

Elements

- A —the state-transition probability matrix

$$a_{ij} = P(q_t = j | q_{t-1} = i) \quad 1 \leq i, j, \leq N$$

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1j} & \cdots & a_{1N} \\ a_{21} & a_{22} & \cdots & a_{2j} & \cdots & a_{2N} \\ \vdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ a_{i1} & a_{i2} & \cdots & a_{ij} & \cdots & a_{iN} \\ \vdots & \vdots & \cdots & \vdots & \cdots & \vdots \\ a_{N1} & a_{N2} & \cdots & a_{Nj} & \cdots & a_{NN} \end{bmatrix}$$

Elements

- B —Observation probability distribution

$$B_j(k) = P(o_t = k | q_t = j) \quad 1 \leq k \leq M$$

- π —Initial state distribution

$$\pi_i = P(q_1 = i) \quad 1 \leq i \leq N$$

Elements

- λ —the entire model

$$\lambda = (A, B, \pi)$$

Assumptions

- First order Markov assumption

$$P(q_t = j | q_{t-1} = i, q_{t-2} = k, \dots) = P(q_t = j | q_{t-1} = i)$$

- Stationarity

$$P(q_t = j | q_{t-1} = i) = P(q_{t+l} = j | q_{t+l-1} = i)$$

- Output Independent

Example

$S = \{\text{stand, walk, run}\}$

$O = \{\text{data1, data2, data3}\}$

$\pi = \{0.5, 0.3, 0.2\}$

$Q = \text{SSWRWWS}$

a_{ij}	Stand	Walk	Run
Stand	0.9	0.7	0.5
Walk	0.6	0.8	0.5
Run	0.4	0.7	0.8

b_{ij}	data1	data2	data3
Stand	0.9	0.2	0.1
Walk	0.2	0.7	0.6
Run	0.1	0.6	0.7

Three Basic Problems

- The Evaluation Problem—Forward Algorithm
- The Decoding Problem—Viterbi Algorithm
- The Learning Problem—Baum-Welch Algorithm

Forward Algorithm

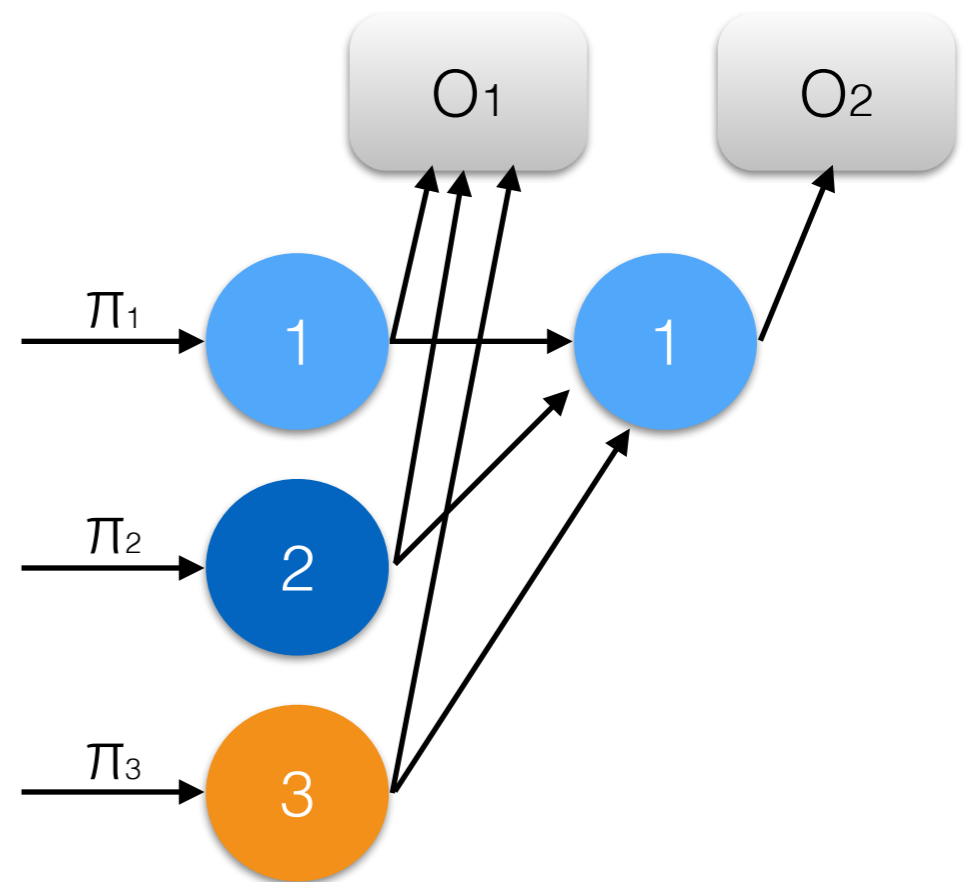
Forward variable $\alpha_t(i)$

$$P(O_1 O_2, q_2 = s_1 | \lambda) = \alpha_1(1) \times a_{11} \times b_1(O_2) + \alpha_1(2) \times a_{21} \times b_1(O_2) + \alpha_1(3) \times a_{31} \times b_1(O_2) = \alpha_2(1)$$

$$\alpha_1(i) = \pi_1 \times b_i(O_1)$$

$$\alpha_{t+1} = \left(\sum_{i=1}^N \alpha_t(i) a_{ij} \right) b_j(O_{t+1})$$

$$P(O | \lambda) = \sum_{i=1}^N \alpha_T(i)$$



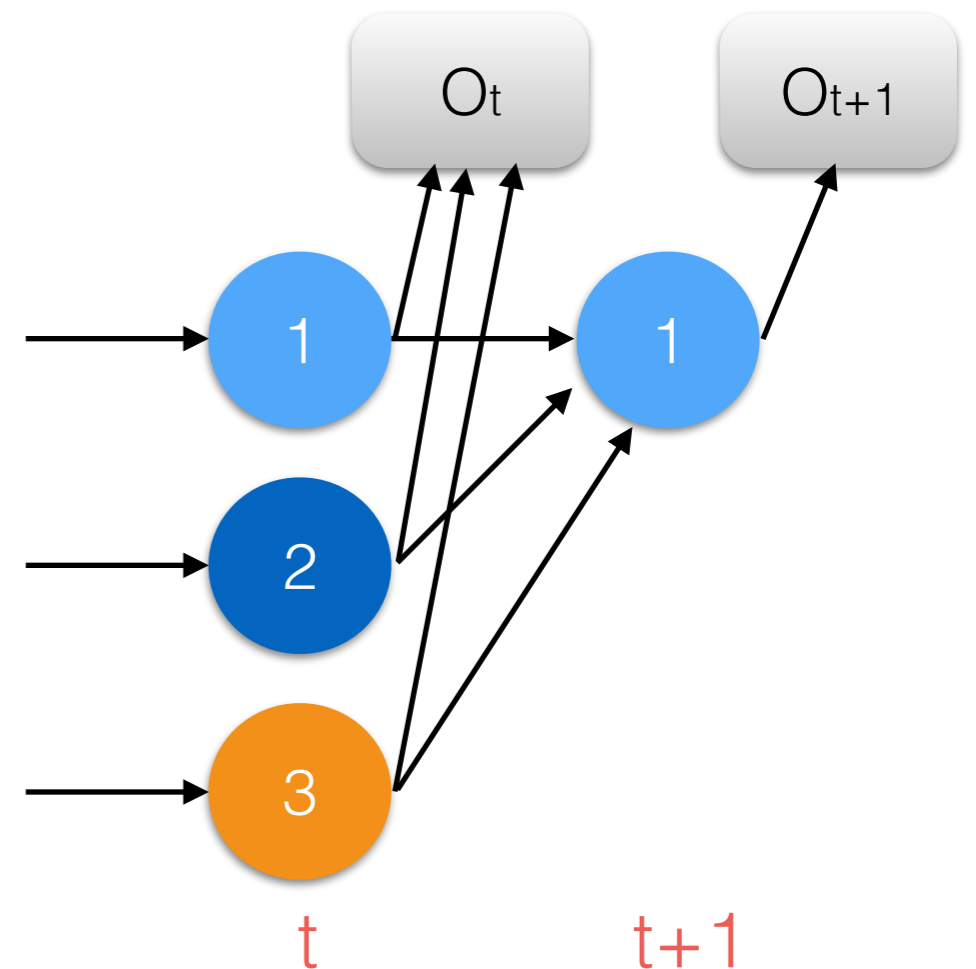
Viterbi Algorithm

Viterbi variable $\delta_t(i)$

$$\delta_t(i) = \max P(q_1 q_2 \dots q_t = s_i, O_1 O_2 \dots O_t | \lambda)$$



$$\delta_{t+1}(i) = \max_j \delta_t(j) \times a_{ji} \times b_i(O_{t+1})$$



Baum-Welch Algorithm

- Given O & S , calculate λ to maximize $P(O|\lambda)$
- E & M steps

$$\begin{aligned} \xi_t(i,j) &= P(q_t=s_i, q_{t+1}=s_j | O, \lambda) \\ &= \frac{P(q_t=s_i, q_{t+1}=s_j, O, \lambda)}{P(O|\lambda)} \\ &= \frac{\alpha_t(i) \times a_{ij} \times b_j(O_{t+1}) \times \beta_{t+1}(j)}{P(O|\lambda)} \\ &= \frac{\alpha_t(i) \times a_{ij} \times b_j(O_{t+1}) \times \beta_{t+1}(j)}{\sum_{i=1}^N \sum_{j=1}^N \alpha_t(i) \times a_{ij} \times b_j(O_{t+1}) \times \beta_{t+1}(j)} \end{aligned}$$

$$r_t(i) = \sum_{j=1}^N \xi_t(i,j)$$

$$\pi_i = r_1(i)$$

$$a_{ij} = \frac{\sum_{t=1}^{T-1} \xi_t(i,j)}{\sum_{t=1}^{T-1} r_t(i)}$$

$$b_j(k) = \frac{\sum_{t=1}^T r_t(j) \times \delta(O_t, v_k)}{\sum_{t=1}^T r_t(j)}$$

Baum-Welch Algorithm

- Step 1: Initialization λ randomly satisfying

$$\sum_{i=1}^N \pi_i = 1$$

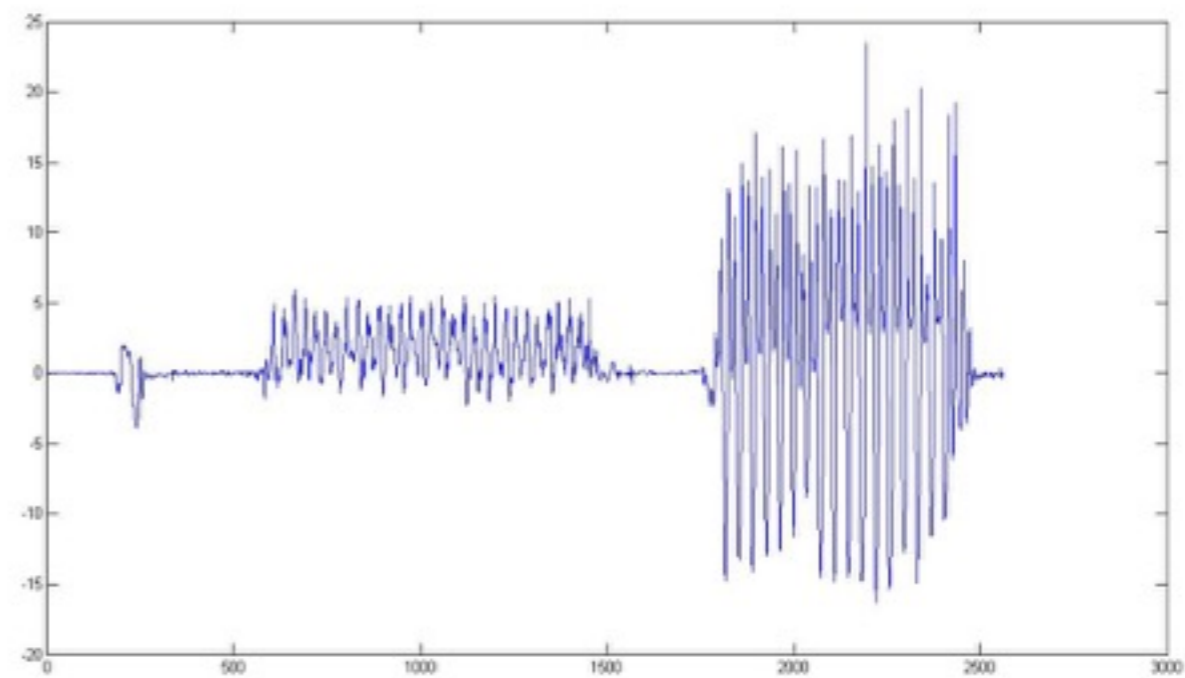
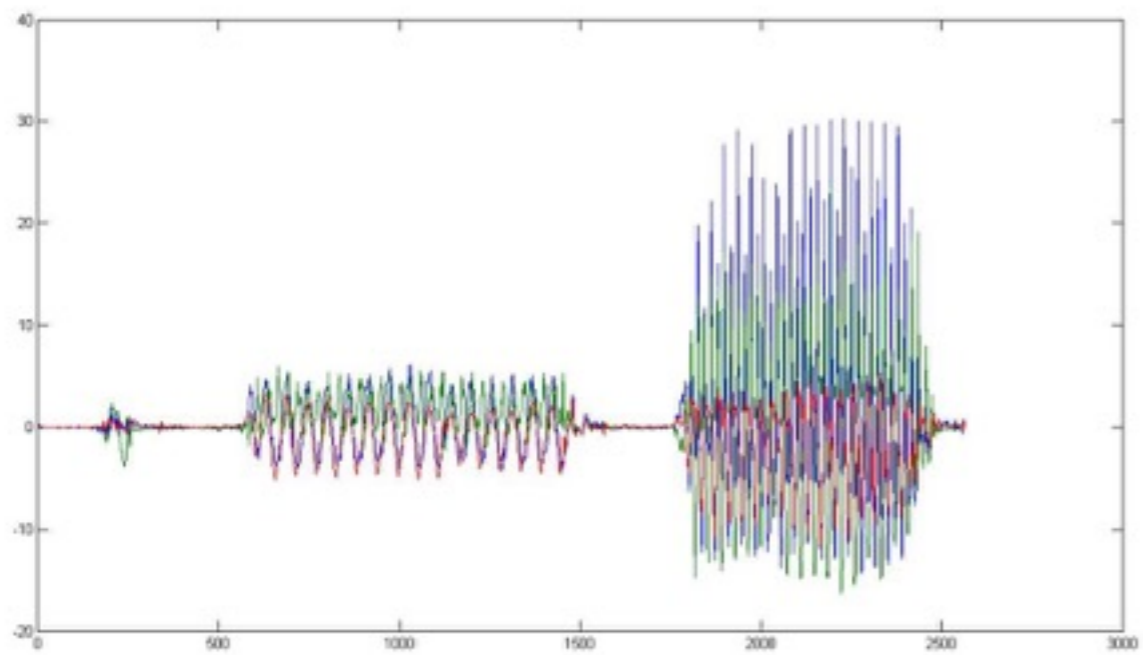
$$\sum_{j=1}^N a_{ij} = 1, 1 \leq i \leq N$$

$$\sum_{k=1}^M b_j(k) = 1, 1 \leq j \leq N$$

- Step 2: Calculate the parameters of E&M
- Step 3: Circulate calculation until convergent

Combination

- Get λ using Baum-Welch Algorithm for our system
- Classify the hidden state according to the data observed



Sit-Sit_Stand-Stand-Walk-Stand-Run

Future Work

- Validation of HMM in our system
- Research focusing on Energy-saving part with Zhuo Li

Thanks

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Thank you